### Stand-by Redundancy

- When primary component fails, standby component is started up.
- Stand-by spares are cold spares => unpowered
- Switching equipment assumed failure free

Let  $X_i$  denote the lifetime of the i-th component from the time it is put into operation until its failure.

System lifetime:

$$X_{sys} = \sum_{i=1}^{n} X_i$$

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### Stand-by Redundancy

- MTTF  $E(X) = \frac{n}{\lambda}$ 
  - gain is linear as a function of the number of components, unlike the case of parallel redundancy
  - added complexity of detection and switching mechanism

### M-of-N System

Starting with N components, we need any M components operable for the system to be operable.

Example: TMR

$$R_{\text{TMR}}(t) = R_1(t)R_2(t)R_3(t) + R_1(t)R_2(t)(1 - R_3(t))$$
  
+  $R_1(t)(1 - R_2(t))R_3(t) + (1 - R_1(t))R_2(t)R_3(t)$ 

Where  $R_i(t)$  is the reliability of the i-th component

if 
$$R_i(t) = R_1(t) = R_2(t) = R_3(t) = R(t)$$
 then
$$R_{\text{TMR}}(t) = R^3(t) + 3R^2(t)(1 - R(t))$$

$$= R^3(t) + 3R^2(t) - 3R^3(t)$$

$$= 3R^2(t) - 2R^3(t)$$

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### M-of-N System

The probability that exactly *j* components are not operating is

$$\binom{N}{j}Q^{j}(t)R^{N-j}(t)$$
 with  $\binom{N}{j} = \frac{N!}{j!(N-j)!}$ 

then

$$R_{MofN}(t) = \sum_{i=0}^{N-M} {N \choose i} Q^{i}(t) R^{N-i}(t)$$

### Reliability Block Diagram

### Series Parallel Graph

- a graph that is recursively composed of series and parallel structures.
- therefore it can be "collapsed" by applying series and/or parallel reduction
- Let  $C_i$  denote the condition that component i is operable
  - 1 = up, 0 = down
- Let S denote the condition that the system is operable
  - 1 = up, 0 = down
- S is a logic function of C's

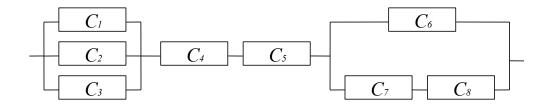
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### Reliability Block Diagram

- Example:



$$S = (C_1 + C_2 + C_3)(C_4C_5)(C_6 + C_7C_8)$$

 $+ \Rightarrow parallel (1 of N)$ 

 $\Rightarrow$  series (N of N)

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## K of N system

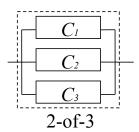
Example 2-of-3 system

$$S = (C_1C_2 + C_1C_3 + C_2C_3)$$

may abbreviate

$$S = \frac{2}{3}(C_1 C_2 C_3)$$

draw as parallel

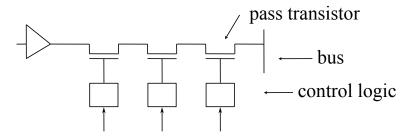


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## Example: Bus-Guardian



- assume  $\lambda$  for transistor & logic  $\lambda = 2 \times 10^{-5}$
- 50/50 split: fail-on/fail-off

Two failure states for system

- •Q<sub>A</sub> = failed active (babbling) with  $\lambda_A$
- •Q<sub>P</sub> = failed passive with  $\lambda_p$

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$$\lambda = 2 \times 10^{-5}$$

$$\lambda_A = 1 \times 10^{-5}$$

$$\lambda_P = 1 \times 10^{-5}$$

$$MTTF = \frac{1}{\lambda} = 5 \times 10^{4}$$

$$MTTF_{A} = \frac{1}{\lambda_{A}} = 10^{5}$$

$$MTTF_{P} = \frac{1}{\lambda_{P}} = 10^{5}$$

for each stage

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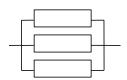
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### Example: Bus-Guardian

#### Active Failure

- if any one bus guardian is correct then no babble possible
- thus we use 1-of-N parallel system model



$$Q(t) = \prod_{i=1}^{3} Q_i(t)$$

with 
$$Q_i(t) = 1 - e^{-\lambda_A t}$$

- Solution Parallel
  - » if any one bus guardian is correct then no babble possible
  - » 1-of-N parallel system model

$$Q(t) = (1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})$$
$$= 1 - 3e^{-\lambda_A t} + 3e^{-2\lambda_A t} - e^{-3\lambda_A t}$$

e.g. with 
$$\lambda_A = 10^{-5} / h$$
 and  $t = 1000h$   
 $\lambda_A t = 0.01$ 

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### Example: Bus-Guardian

compute: 
$$Q(t) = 1 - 3e^{-\lambda_A t} + 3e^{-2\lambda_A t} - e^{-3\lambda_A t}$$

$$Q(1000h) = 1 - 3(0.9900498) + 3(0.9801987) - (0.9704455)$$
$$= 1.2 \times 10^{-6}$$

compute:

$$Q(t) = (1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})$$
$$= (1 - e^{-\lambda_A t})^3$$

 $Q(1000h) = 0.9851243 \times 10^{-6}$ 

in general: danger of cancellation

- => catastrophic results,
- => legal issues (even though one should realize what the fail rates really mean)

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$$MTTF_{A} = \int_{0}^{\infty} R(t)dt = \int_{0}^{\infty} 1 - Q(t)dt$$

$$= \int_{0}^{\infty} (3e^{-\lambda_{A}t} - 3e^{-2\lambda_{A}t} + e^{-3\lambda_{A}t})dt$$

$$= \left[ -\frac{3}{\lambda_{A}} e^{-\lambda_{A}t} + \frac{3}{2\lambda_{A}} e^{-2\lambda_{A}t} - \frac{1}{3\lambda_{A}} e^{-3\lambda_{A}t} \right]_{0}^{\infty}$$

simplification:

$$e^{-\lambda_A t} = 0 \text{ as } t \to \infty$$
  
 $e^{-\lambda_A t} = 1 \text{ with } t = 0$ 

MTTF<sub>A</sub> =  $\frac{3}{\lambda_A} - \frac{3}{2\lambda_A} + \frac{1}{3\lambda_A}$ =  $(3 - \frac{3}{2} + \frac{1}{3}) \times 10^5$ =  $1.83 \times 10^5 h$ Page: 13 CS449/549 Fault-

3 drivers result in approx. MTTF of twice and not three times that of single driver

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### Example: Bus-Guardian

#### Passive Failure

- any one of N bus guardians can take out subsystem
- thus we use series system model

$$\frac{3}{12} = \frac{3}{12} = \frac{3}{12}$$

$$R(t) = \prod_{i=1}^{3} R_i(t)$$

$$= e^{-\sum_{i=1}^{3} \lambda_i t}$$

$$= e^{-3\lambda t}$$
Given  $\lambda = 1 \times 10^{-5}$   $t = 1000h$ 

$$R(t) = e^{-3\lambda t} = 0.9704455$$

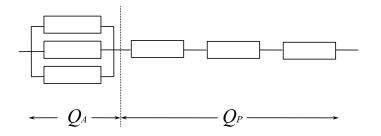
$$\Rightarrow MTTF = \frac{1}{\lambda_{sysp}} = 333333h$$

$$= e^{-3\lambda t}$$

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- summary
  - active failure  $\Rightarrow$  parallel  $\Rightarrow$   $Q_A$
  - passive failure => series =>  $Q_P$
  - whole system fails if either mode occurs => series



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### Example: Bus-Guardian

### summary

	Simplex	Triplex
$MTTF_{_A}$	$1 \times 10^5 h$	$1.8 \times 10^5 h$
$MTTF_{P}$	$1 \rtimes 0^5 h$	$0.33 \times 10^5 h$
MTTF	$0.5 \times 10^5 h$	$0.28 \times 10^5 h$

$$MTTF = \frac{MTTF_{\scriptscriptstyle A} \times MTTF_{\scriptscriptstyle P}}{MTTF_{\scriptscriptstyle A} + MTTF_{\scriptscriptstyle P}}$$

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### What is the unreliability $Q_A$ ?

◆ Two approaches to compute Q(t) at 1000h

1) 
$$Q(t) = (1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})$$
$$= 1 - 3e^{-\lambda_A t} + 3e^{-2\lambda_A t} - e^{-3\lambda_A t}$$

2) 
$$MTTF_A = 1.8333 \times 10^5$$
  
using  $MTTF = \frac{1}{\lambda}$  we compute  $\lambda$  and use  $Q(t) = (1 - e^{-\lambda t})$ 

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Now we compute Q(1000) and ...

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What is wrong?